

School of Electronics and Computer Science

### ESBMC 5.0

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### MOTIVATION

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 Battleship built in 1946 and automated in 1996 (27 dual-core 200MHz processors and Windows NT).

#### **USS Yorktown**

### Motivation



#### **USS Yorktown**

- Battleship built in 1946 and automated in 1996 (27 dual-core 200MHz processors and Windows NT).
- Failure due to a division by zero: It had to be towed back to its naval base.

### SOFTWARE VERIFICATION TECHNIQUES



- Checks only some of the system executions.
- May miss errors.
- Can be less expensive than model checking.



- Can be bounded to limit number of iterations, context-switch, etc.
- Report errors as traces.
- Can be extremely resource-hungry.

### **Bounded Model checking**



- Bounded model checkers "slice" the state space in depth.
- It's aimed to find bugs and (naïvely) can only prove correctness if all states are reachable within the bound.

### **ESBMC 5.0**

# ESBMC 5.0

- ESBMC, the Efficient SMT-Based Context-Bounded Model Checker was originally developed at Southampton by Lucas Cordeiro under the supervision of Bernd Fischer.
- Jeremy Morse further developed ESBMC during his PhD.
- Development is now led from Southampton by Mikhail Gadelha.
- Turned 10 years in 2018!

# ESBMC 5.0

- SMT-based BMC of single- and multi-threaded C/C++ programs.
- exploits SMT solvers and their background theories:
  - optimized encodings for pointers, bit operations, unions, arithmetic over- and underflow, and floatingpoints,
  - support for Boolector, Z3, MathSAT, CVC4 and Yices.
- supports verifying multi-threaded software that uses pthreads threading library:

– lazy exploration of the reachability tree.

# **Supported Properties**

- built-in properties:
  - arithmetic under- and overflow,
  - pointer safety,
  - array bounds,
  - division by zero,
  - memory leaks,
  - atomicity and order violations,
  - deadlock,
  - data race.

### **K-INDUCTION**

# *K*-induction: we can sometimes analyse to unbounded depths

- In general, there is no way to deduce depths:
  - halting problem,
  - lots of current work on deducing invariants.
- For simple loops, they can sometimes be guessed.
- Interval analysis often speed up the analysis considerably.

# K-induction: the proof falls into three parts

- 1. Base case: naïve BMC, tries to find bugs.
- 2. Forward condition: checks the completeness threshold (if all loops were completely unrolled).
- 3. Inductive step: over-approximate loops so all states can be checked without unrolling them completely (sometime it helps to unroll a few times to strengthen invariants).

### **FLOATING-POINTS**

## Floating-points: can it fail?

int main() { float x; float y = x;assert (x == y);return 0;

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## Floating-points: can it fail?

int main() { float x = NaN;float y = x;assert (x == y);return 0; ł

# **Floating-point Encoding**

- ESBMC encodes floating-point arithmetic using:
  - bitvectors, which extends the floating-point arithmetic support to all solvers that are currently integrated.
  - the SMT theory of floating-points, available only in Z3 and MathSAT.

### **PYTHON API**

# Python API

- ESBMC now includes a **Python API** that reduces the difficulty of prototyping new features and makes the tool internals accessible to a wider audience.
- The verification process can be intercepted and modified: we currently use the process to call Matlab and generate the transfer functions of digital systems.

# **Experimental Evaluation**

- Our evaluation consists of 9523 benchmarks from SV-COMP'18, checking a range of properties:
  - Reachability in single- and multi-threaded programs,
  - Memory safety,
  - Overflow,
  - Termination.

# **Experimental Evaluation**

• ESBMC ranked third in the overall category, with a 5476 score.

• The k-induction algorithm reported 4301 correct results, the best result among tools that used *k*-induction in the competition.

• 92% of witnesses being correctly validated.

# Experimental Evaluation (floating-points)



## Thank you

www.esbmc.org

https://github.com/esbmc/esbmc

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